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First-order stable and causal hydrodynamics from kinetic theory

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<u>Motivation</u>

- In relativistic heavy-ion collisions, a deconfined state of matter is produced, known as Quark-Gluon Plasma (QGP).
- The kinetic theory and hydrodynamics have been essential effective models to understand the evolution of this system.
- Relativistic generalization of Navier-Stokes equations known to be acausal and unstable - Higher order theories are introduced.
- ✤ A new solution to the causality and stability problems for *first-order theory* recently proposed by Bemfica, Disconzi, Noronha, and Kovtun (BDNK).

<u>Microscopic Theory</u>

The relativistic Boltzmann transport equation:

 $p^{\mu}\partial_{\mu}f(x,p) = C[f] = \int d\Gamma_{p_1}d\Gamma_{p'}d\Gamma_{p'_1}\left[f_{p'}f_{p'_1}\left(1\pm f_p\right)\left(1\pm f_{p_1}\right) - f_pf_{p_1}\left(1\pm f_{p'}\right)\left(1\pm f_{p'_1}\right)\right]W(p'p'_1|pp_1)$

The distribution function for small deviation from local equilibrium:

$$f_p = f_p^{(0)} + \delta f_p, \ \delta f_p = f_p^{(0)} (1 \pm f_p^{(0)}) \phi_p$$

The collision operator in linear order becomes:

$$C[f] = -\mathcal{L}[\phi] = \int d\Gamma_{p_1} d\Gamma_{p'} d\Gamma_{p'_1} f_p^{(0)} f_{p_1}^{(0)} (1 \pm f_{p'}^{(0)}) (1 \pm f_{p'_1}^{(0)}) [\phi_p + \phi_{p_1} - \phi_{p'_1} - \phi_{p'_1}] W(p'p'_1|pp_1)$$

Properties of the linearized collision operator:

Self-Adjoint

Microscopic Conservation

Summation Invariant

$$\int d\Gamma_p \psi \mathcal{L}[\phi] = \int d\Gamma_p \phi \mathcal{L}[\psi] \qquad \mathcal{L}[a + b_\mu p^\mu] = 0 \qquad \int d\Gamma_p \mathcal{L}[\phi] = 0, \quad \int d\Gamma_p p^\mu \mathcal{L}[\phi] = 0$$

The out-of-equilibrium distribution function

In general, the out-of-equilibrium distribution function can be expressed as <u>S. R. de Groot, Relativistic Kinetic Theory</u>

$$\phi^{(r)} = \sum_{l} A_{l}^{(r)} X^{(r)l} + \sum_{m} B_{m}^{(r)\mu} Y_{\mu}^{(r)m} + \sum_{n} C_{n}^{(r)\mu\nu} Z_{\mu\nu}^{(r)n}$$

- Field gradients: $X^{(r)l}, Y^{(r)m}, Z^{(r)n}_{\mu\nu}$
- The unknown coefficients: $A_l^{(r)}, B_m^{(r)\mu}, C_n^{(r)\mu\nu}$

The unknown coefficients are the function of space-time, particle momentum, rest mass and temperature. We expand the coefficients a polynomial basis as:

$$A_{l}^{(r)} = \sum_{s=0}^{\infty} A_{l}^{r,s}(z,x) P_{s}^{(0)} \qquad B_{m}^{(r)\mu} = \sum_{s=0}^{\infty} B_{m}^{r,s}(z,x) P_{s}^{(1)} \tilde{p}^{\langle \mu \rangle} \qquad C_{n}^{(r)\mu\nu} = \sum_{s=0}^{\infty} C_{n}^{r,s}(z,x) P_{s}^{(2)} \tilde{p}^{\langle \mu} \tilde{p}^{\nu \rangle}$$

Hydrodynamic Frame

General hydrodynamic frame or general matching conditions:

$$\int dF_{\rm p}\tilde{E}_{\rm p}^{i}\phi = 0, \ \int dF_{\rm p}\tilde{E}_{\rm p}^{j}\phi = 0, \ \int dF_{\rm p}\tilde{E}_{\rm p}^{k}\tilde{p}^{\langle\mu\rangle}\phi = 0$$

For Landau-Lifshitz (LL) frame (i,j,k) = (2,1,1) and for Eckart frame (i,j,k) = (2,1,0).

For the properties of linearized collision operator, we can't determine homogeneous solutions from transport equation. Using **general matching** conditions we calculate the **homogeneous part**:

$$A_{l}^{r,0} = -\frac{1}{\mathcal{D}_{i,j}^{0,1}} \sum_{s=2}^{\infty} \mathcal{D}_{i,j}^{s,1} A_{l}^{r,s}, \quad A_{l}^{r,1} = -\frac{1}{\mathcal{D}_{i,j}^{1,0}} \sum_{s=2}^{\infty} \mathcal{D}_{i,j}^{s,0} A_{l}^{r,s}, \quad B_{m}^{r,0} = -\frac{1}{J_{k}} \sum_{s=1}^{\infty} J_{k+s} B_{m}^{r,s}$$

The rests are known as **inhomogeneous/interaction** solution can be estimated from the transport equation.

$$\mathcal{D}_{i,j}^{m,n} = I_{i+m}I_{j+n} - I_{i+n}I_{j+m} \qquad I_n = \int dF_p \tilde{E}_p^n, \Delta^{\mu\nu}J_n = \int dF_p \tilde{p}^{\langle\mu\rangle} \tilde{p}^{\langle\nu\rangle} \tilde{E}_p^n$$

Homogeneous and Inhomogeneous Solution

The entire out-of-equilibrium distribution function for any order can be determined separately for **frame (homogeneous)** and **interaction (inhomogeneous)** parts as:

$$\phi^{(r)} = \phi_{\rm int}^{(r)} + \phi_{\rm h}^{(r)}$$

The homogeneous part:

$$\phi_{\mathbf{h}}^{(r)} = -\tilde{E}_{\mathbf{p}} \left[\frac{I_j}{\mathcal{D}_{i,j}^{1,0}} \int dF_p \tilde{E}_{\mathbf{p}}^i \phi_{\mathrm{int}}^{(r)} + (i \leftrightarrow j) \right] - \left[\frac{I_{j+1}}{\mathcal{D}_{i,j}^{0,1}} \int dF_p \tilde{E}_{\mathbf{p}}^i \phi_{\mathrm{int}}^{(r)} + (i \leftrightarrow j) \right] - \frac{\tilde{p}_{\langle \nu \rangle}}{J_k} \int dF_p \tilde{E}_{\mathbf{p}}^k \tilde{p}^{\langle \nu \rangle} \phi_{\mathrm{int}}^{(r)}$$

The inhomogeneous/interaction part:

 $\phi_{\rm int}^{(r)} = \sum_{l} \sum_{s=2}^{\infty} A_l^{r,s} P_s^{(0)} X^{(r)l} + \sum_{m} \sum_{s=1}^{\infty} B_m^{r,s} P_s^{(1)} \tilde{p}^{\langle \mu \rangle} Y_{\mu}^{(r)m} + \sum_{n} \sum_{s=0}^{\infty} C_n^{r,s} P_s^{(2)} \tilde{p}^{\langle \mu} \tilde{p}^{\mu \rangle} Z_{\mu\nu}^{(r)n}$

Tensor decomposition of energy-momentum and particle current

General expressions for energy-momentum tensor and particle four-current:

$$T^{\mu\nu} = (\epsilon_0 + \delta\epsilon) u^{\mu} u^{\nu} - (P_0 + \delta P) \Delta^{\mu\nu} + (W^{\mu} u^{\nu} + W^{\nu} u^{\mu}) + \pi^{\mu\nu} \qquad N^{\mu} = (n_0 + \delta n) u^{\mu} + V^{\mu}$$

In kinetic theory, the energy-momentum tensor and particle four-current defined as:

$$T^{\mu\nu} = \int d\Gamma_{\rm p} p^{\mu} p^{\nu} f(x, p) \qquad \qquad N^{\mu} = \int d\Gamma_{\rm p} p^{\mu} f(x, p)$$

From the general tensor decomposition it follows:

$$\epsilon_{0} = \int d\Gamma_{p} E_{p}^{2} f_{p}^{(0)} \qquad \qquad n_{0} = \int d\Gamma_{p} E_{p} f_{p}^{(0)}$$
$$W^{\mu} = \int d\Gamma_{p} E_{p} p^{\langle \mu \rangle} \delta f_{p} \qquad \qquad V^{\mu} = \int d\Gamma_{p} p^{\langle \mu \rangle} \delta f_{p}$$

System Dynamics

We use the momentum-dependent relaxation time approximation (*MDRTA*) for solving the relativistic transport equation as a model study.

$$\tilde{p}^{\mu}\partial_{\mu}f = -\frac{\tilde{E}_{\rm p}}{\tau_R}f^{(0)}(1\pm f^{(0)})\phi_{\rm int} \qquad \tau_R(x,p) = \tau_R^0(x)\tilde{E}_{\rm p}^{\Lambda}$$

Appropriate collision kernel:

$$\mathcal{L}_{\text{MDRTA}}[\phi] = \frac{(p \cdot u)}{\tau_R} f^{(0)}(1 \pm f^{(0)}) \bigg[\phi - \frac{\langle \frac{\tilde{E}_p}{\tau_R} \tilde{E}_p^2 \rangle \langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle - \langle \frac{\tilde{E}_p}{\tau_R} \tilde{E}_p \rangle \langle \frac{\tilde{E}_p}{\tau_R} \phi \tilde{E}_p \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \tilde{E}_p^2 \rangle - \langle \frac{\tilde{E}_p}{\tau_R} \tilde{E}_p^2 \rangle^2} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle - \langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \tilde{E}_p^2 \rangle - \langle \frac{\tilde{E}_p}{\tau_R} \tilde{E}_p^2 \rangle^2} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle - \langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \tilde{E}_p^2 \rangle - \langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle - \langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle}{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{\langle \frac{\tilde{E}_p}{\tau_R} \phi \rangle} - \tilde{E}_p \frac{$$

The inhomogeneous/interaction part:

Rocha et al., arXiv: 2205.00078

$$\phi_{\rm int}^{(1)} = -\tau_R^0 \tilde{E}_{\rm p}^{\Lambda-1} \left[\tilde{E}_{\rm p}^2 \frac{DT}{T} + \tilde{E}_{\rm p} D\tilde{\mu} + \left(\frac{\tilde{E}_{\rm p}^2}{3} - \frac{z^2}{3} \right) (\partial \cdot u) + \tilde{E}_{\rm p} \tilde{p}^{\langle \mu \rangle} \left(\frac{\nabla_{\mu} T}{T} - D u_{\mu} \right) + \tilde{p}^{\langle \mu \rangle} \nabla_{\mu} \tilde{\mu} - \tilde{p}^{\langle \mu \rho \rangle} \sigma_{\mu\nu} \right]$$

First-Order Field Redefinition

The first-order thermodynamic field corrections in a general frame written as:

$$\delta \epsilon^{(1)} = \varepsilon_1 \frac{DT}{T} + \varepsilon_2 \left(\partial \cdot u \right) + \varepsilon_3 D\tilde{\mu}$$

$$\delta P^{(1)} = \pi_1 \frac{DT}{T} + \pi_2 \left(\partial \cdot u \right) + \pi_3 D\tilde{\mu}$$

$$V^{(1)\mu} = \gamma_1 \left(\frac{\nabla^{\mu}T}{T} - Du^{\mu} \right) + \gamma_3 \nabla^{\mu} \tilde{\mu}$$

$$F. S. Bemfica et al., PRD 100, 104020 (2019) P. Kovtun, JHEP 10, 034 (2019) OP ($$

Not **all transport coefficients are invariant** under the general first-order field redefinition, the invariant ones are:

$$f_{i} = \pi_{i} - \varepsilon_{i} \left(\frac{\partial P_{0}}{\partial \epsilon_{0}}\right)_{n_{0}} - \nu_{i} \left(\frac{\partial P_{0}}{\partial n_{0}}\right)_{\epsilon_{0}} \qquad l_{i} = \gamma_{i} - \frac{n_{0}}{\epsilon_{0} + P_{0}}\theta_{i}$$

$$\zeta = -f_{2} + \left(\frac{\partial P_{0}}{\partial \epsilon_{0}}\right)_{n_{0}} f_{1} + \frac{1}{T} \left(\frac{\partial P_{0}}{\partial n_{0}}\right)_{\epsilon_{0}} f_{3} \qquad k_{n} = l_{3} - \frac{n_{0}T}{\epsilon_{0} + P_{0}}l_{1}$$

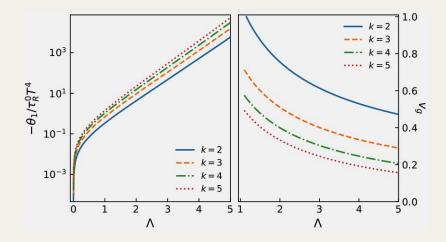
$$\eta$$

The detailed expressions of bulk and shear viscosity and heat conductivity are given in <u>S. Mitra, PRC 105, 014902 (2022)</u> **Shear Channel**

The stability criteria is:

The causality criteria is:

$$\begin{split} \theta_{1} &= -\tau_{R}^{0} T^{2} \left(J_{\Lambda+1} + \frac{\epsilon_{0} + P_{0}}{T^{2}} \frac{J_{k+\Lambda}}{J_{k}} \right) < 0 \\ v_{g} &= \sqrt{\frac{\eta}{\theta}} < 1 \qquad \textit{Here} \qquad \theta = -\theta_{1} \end{split}$$



For certain range of microscopic interactions, the shear channel become acausal.

Sound Channel

Using **Routh-Hurwitz criteria**, we find the following conditions for **stability** of the sound channel are:

$$A_6 > 0$$
, $A_5 > 0$, $A_3^0 > 0$, $B_2 = (A_4^0 A_5 - A_3^0 A_6)/A_5 > 0$

All A_i are function of the transport coefficients. Here we show few transport coefficients:

$$\varepsilon_{1} = \tau_{R}^{0} \left[\frac{\partial \epsilon_{0}}{\partial \tilde{\mu}} \frac{\mathcal{D}_{i,j}^{\Lambda+1,1}}{\mathcal{D}_{i,j}^{0,1}} + T \frac{\partial \epsilon_{0}}{\partial T} \frac{\mathcal{D}_{i,j}^{\Lambda+1,0}}{\mathcal{D}_{i,j}^{1,0}} - T^{2} I_{\Lambda+3} \right]$$

$$\varepsilon_{3} = \tau_{R}^{0} \left[\frac{\partial \epsilon_{0}}{\partial \tilde{\mu}} \frac{\mathcal{D}_{i,j}^{\Lambda,1}}{\mathcal{D}_{i,j}^{0,1}} + T \frac{\partial \epsilon_{0}}{\partial T} \frac{\mathcal{D}_{i,j}^{\Lambda,0}}{\mathcal{D}_{i,j}^{1,0}} - T^{2} I_{\Lambda+2} \right]$$

$$\nu_{1} = \tau_{R}^{0} \left[\frac{\partial n_{0}}{\partial \tilde{\mu}} \frac{\mathcal{D}_{i,j}^{\Lambda+1,1}}{\mathcal{D}_{i,j}^{0,1}} + T \frac{\partial n_{0}}{\partial T} \frac{\mathcal{D}_{i,j}^{\Lambda+1,0}}{\mathcal{D}_{i,j}^{1,0}} - T I_{\Lambda+2} \right]$$

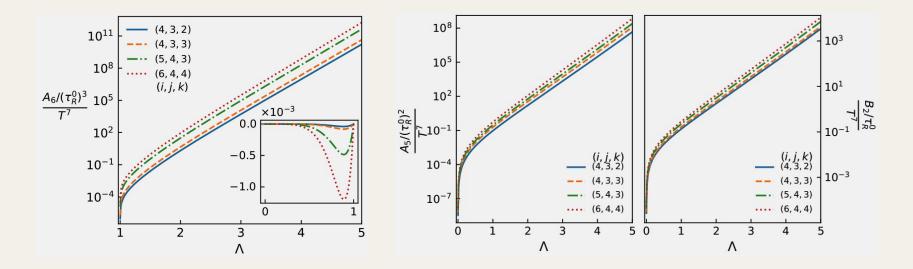
$$\nu_{3} = \tau_{R}^{0} \left[\frac{\partial n_{0}}{\partial \tilde{\mu}} \frac{\mathcal{D}_{i,j}^{\Lambda,1}}{\mathcal{D}_{i,j}^{0,1}} + T \frac{\partial n_{0}}{\partial T} \frac{\mathcal{D}_{i,j}^{\Lambda,0}}{\mathcal{D}_{i,j}^{1,0}} - T I_{\Lambda+1} \right]$$

 $\succ \varepsilon_1, \nu_1$ vanish both for i=1, j=2 (LL+Eckart) for all Λ , and also at $\Lambda = 0$ for all frame.

 $\succ \quad \varepsilon_3, \nu_3 \quad obey \ the \ same \ but \ also \ vanish \ for \ \Lambda = 1 \ at \ all \ frames.$

Sound Channel

The coefficients make A_5 and A_4^0 vanish for $\Lambda = 0$ and A_6 vanish for both $\Lambda = 0$ and 1 at any frame.



Also the stability of sound modes becomes unstable for certain range of microscopic interactions.

Conclusion

- ✤ A first-order, relativistic stable and causal hydrodynamic theory has been derived in a general frame from the Boltzmann transport equation
- We have shown that in order to hold stability and causality at first-order theories, besides a general frame, the system interactions need to be carefully taken into account.
- The conventional momentum independent RTA leads to acausality in general frame.

Thank You!!